SAFETY MANUAL



SH 8384-0 EN

Translation of original instructions



Type 3730-0 Electropneumatic Positioner



Definition of signal words

▲ DANGER

Hazardous situations which, if not avoided, will result in death or serious injury

A WARNING

Hazardous situations which, if not avoided, could result in death or serious injury

• NOTICE

Property damage message or malfunction

i Note

Additional information

-\rac{\tip}

Recommended action

Purpose of this manual

The Safety Manual SH 8384-0 contains information relevant for the use of the Type 3730-0 Positioner in safety-instrumented systems according to IEC 61508 and IEC 61511. The safety manual is intended for planners, constructors and operators of safety-instrumented systems.

NOTICE

Risk of malfunction due to incorrect mounting, connection or start-up of the positioner.

- → Refer to the Mounting and Operating Instructions EB 8384-0 on how to mount the positioner, perform the electric and pneumatic connections as well as start up the positioner.
- → Observe the warnings and safety instructions written in the Mounting and Operating Instructions EB 8384-0.

Further documentation

The documents listed below contain descriptions of the start-up, functioning and operation of the positioner. You can download these documents from the SAMSON website.

Type 3730-0 Positioner

► T 8384-0: Data Sheet

► EB 8384-0: Mounting and Operating Instructions



In addition to the positioner documentation, observe the documentation for the pneumatic actuator, valve and other valve accessories.

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1 Scope

1.1 General

The Type 3730-0 Electropneumatic Positioner is a single-acting positioner for mounting on pneumatic linear actuators with spring-return mechanism. The positioner is used to position control valves.

1.2 Use in safety-instrumented systems

Observing the requirements of IEC 61508, the systematic capability of the pilot valve for emergency venting as a component in safety-instrumented systems is given.

Use of the positioner is possible on observing the requirements of IEC 61511 and the required hardware fault tolerance in safety-instrumented systems up to SIL 2 (single device/HFT = 0) and SIL 3 (redundant configuration/HFT = 1).

The positioner is regarded as a type A device according to IEC 61508-2 in view of its safety functions.

1.3 Versions and ordering data

All versions of the Type 3730-0 Positioner are suitable for use in safety-instrumented systems.

1.4 Attachment

The positioner is suitable for the following types of attachment in combination with various mounting parts:

- Direct attachment to SAMSON Type 3277 Linear Actuators
- Attachment to linear actuators according to IEC 60534-6 (NAMUR)
- Attachment to linear actuators according to VDI/VDE 3847
- Attachment to SAMSON Type 3510 Micro-flow Valve

2 Technical data

Type 3730-0 Positioner: the technical data for the explosion-protected devices may be restricted by the limits specified in the test certificates.				
Rated travel	Adjustable: Direct attachment to Type 3277: 5.3 to 30 mm Attachment according to IEC 60534-6: 5.3 to 200 mm			
Travel range	Adjustable within the rated travel, max. ratio 1:5			
Set point w	4 to 20 mA signal range Split-range operation 4 to 12 mA and 12 to 20 mA, selected at the DIP switch Two-wire device, reverse polarity protection, static destruction limit 100 mA			
Minimum current	>3.6 mA			
Load impedance	Version without explosion protection: ≤ 6 V (corresponding to 300 Ω at 20 mA) Explosion-protected version: ≤ 6 V			
Supply Supply air Air quality acc. to ISO 8573-1 (edition 2001-02):	1.4 to 7 bar (20 to 105 psi) Max. particle size and density: Class 4 Oil content: Class 3 · Pressure dew point: Class 3 or at least 10 K below the lowest ambient temperature to be expected			
Signal pressure (output)	O bar up to the supply pressure Limitation to approx. 2.4 bar enabled by setting DIP switch			
Characteristic	Linear, deviation from characteristic ≤ 1 %			
Hysteresis	≤1 %			
Sensitivity	≤0.1 %			
Direction of action	Selectable over DIP switch			
Air consumption, steady state	Independent from supply pressure approx. 120 l _n /h			
Air output capacity Actuator (supply) Actuator (exhaust)	At $\Delta p = 6$ bar: $8.5 \text{ m}_n^3/\text{h}$ · At $\Delta p = 1.4$ bar: $3.0 \text{ m}_n^3/\text{h}$ · $K_{V_{max}(20 ^{\circ}C)} = 0.09$ At $\Delta p = 6$ bar: $14.0 \text{ m}_n^3/\text{h}$ · At $\Delta p = 1.4$ bar: $4.5 \text{ m}_n^3/\text{h}$ · $K_{V_{max}(20 ^{\circ}C)} = 0.15$			
Permissible ambient tem- perature	-20 to +80 °C -45 to +80 °C with metal cable gland The temperature limits for the explosion-protected devices may be restricted by the limits specified in the test certificates.			
Influences	Temperature: ≤0.15 %/10 K Supply air: none Vibrations: ≤ 0.25 % up to 2000 Hz and 4 g according to IEC 770			
Electromagnetic compatibility	Complying with EN 61000-6-2, EN 61000-6-3, EN 61326-1 and NAMUR Recommendation NE 21			
Use in safety-instrumented systems acc. to IEC 61508	Suitable for use in safety-instrumented systems up to SIL 2 (single device) and SIL 3 (with redundant configuration) Emergency shutdown at a set point of 0 mA			

Type 3730-0 Positioner: the technical data for the explosion-protected devices may be restricted by the limits specified in the test certificates.				
Degree of protection	IP 66			
Materials	Die-cast aluminum EN AC-AlSi12(Fe) (EN AC-44300) according to DIN EN 1706, chromated and plastic coated External parts: stainless steel 1.4404/316L			
Weight	Approx. 1 kg			
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3 Safety-related functions

Emergency venting over the i/p converter (Fig. 2 path ———)

In automatic mode, the PD controller (3) compares the valve position to the DC control signal from 4 to 20 mA issued by the microcontroller. In case of a system deviation, the activation of the i/p converter is changed so that the actuator (1) is either vented or supplied with air. Fail-safe action is triggered and the actuator is vented when no signal (0 mA) is applied to terminals 11/12 and, as a result, to the i/p converter.

3.1 Fail-safe action

Fail-safe action is triggered by the i/p converter and upon supply air failure. The positioner fully discharges its pneumatic output to the atmosphere, causing the mounted actuator to be vented. As a result, the valve moves to the fail-safe position. The fail-safe position depends on how the springs are arranged in the pneumatic actuator (air-to-close or air-to-open).

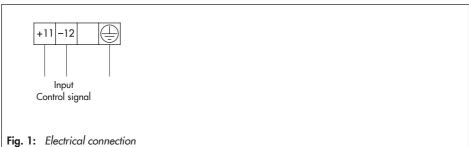
3.2 Protection against unauthorized changes to the configuration

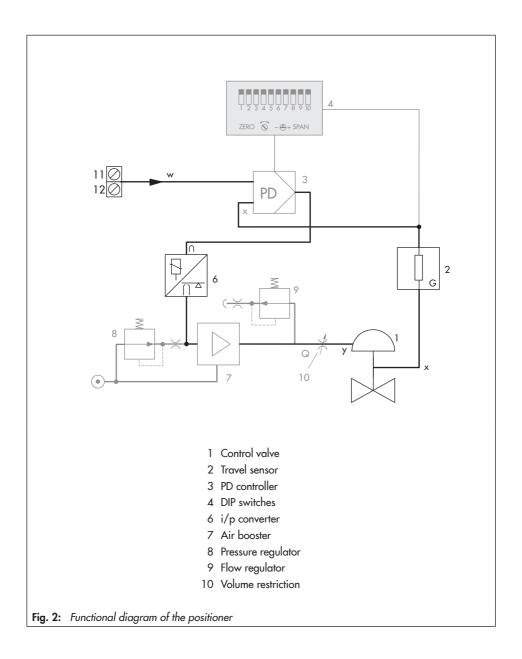
A change to the configuration cannot affect the safety function nor cause it to be deactivated.

4 Mounting, connection and start-up

Refer to Mounting and Operating Instructions EB 8384-0 on how to mount, perform the electric and pneumatic connections as well as start up the positioner.

Only use the specified original mounting parts and accessories.





5 Required conditions

A WARNING

Risk of malfunction due to incorrect selection or wrong installation and operating conditions.

→ Only use control valves in safety-instrumented systems if the necessary conditions in the plant are fulfilled. The same applies to the mounted positioner.

5.1 Selection

- → The required transit times of the control valve are observed.
 The transit times to be implemented are determined by the process engineering requirements.
- → The positioner is suitable for the prevailing ambient temperature.

Versions	Temperature range	
All	−20 to +80 °C	
With metal cable gland	-45 to +80 °C	

The temperature limits for the explosion-protected devices may be further restricted by the limits specified in the test certificates.

→ The temperature limits are observed.

5.2 Mechanical and pneumatic installation

- → The positioner is mounted properly as described in the mounting and operating instructions and connected to the air supply.
- → The maximum supply pressure does not exceed 7 bar.
- → The pneumatic air supply meets the instrument air specifications.

Particle size and quantity	Oil content	Pressure dew point	
Class 4	Class 3	Class 3	
≤ 5 µm and 1000/m³	≤ 1 mg/m³	or at least 10 K below the lowest ambient temperature to be expected	



We recommend installing a supply pressure regulator/filter upstream of the positioner. For example, the SAMSON Type 4708 Supply Pressure Regulator with 5 µm filter cartridge can be used.

- → The supply air line has a minimum inside diameter of 4 mm.
 Select the cross section and length of the line to ensure that the supply pressure at the positioner on supplying air to the actuator does not fall below the minimum limit.
- → The positioner is mounted as prescribed.
- → The vent opening at the back of the positioner remains open when the positioner is installed on site.

5.3 Electrical installation

- → The positioner is connected to the electric power supply properly as described in the mounting and operating instructions.
- → Only cables whose outside diameters are suitable for the cable glands are used.
- → The electrical cables in Ex i circuits comply with the data that planning was based on.
- → The cable glands and cover screws are fastened tightly to ensure that the degree of protection is met.
- The installation requirements for the applicable explosion protection measures are observed.
- → The special conditions specified in the explosion protection certificates are observed.

6 Proof testing

The proof test interval and the extent of testing lie within the operator's responsibility. The operator must draw up a test plan, in which the proof tests and the interval between them are specified. We recommend summarizing the requirements of the proof test in a checklist.

A WARNING

Risk of dangerous failure due to malfunction in the event of emergency (actuator is not vented or the valve does not move to the fail-safe position).

Only use devices in safety-instrumented systems that have passed the proof test according to the test plan drawn up by the operator.

Regularly check the safety-instrumented function of the entire SIS loop. The test intervals are determined, for example on calculating each single SIS loop in a plant (PFD_{ava}).

6.1 Visual inspection to avoid systematic failure

To avoid systematic failure, inspect the positioner regularly. The frequency and the scope of the inspection lie within the operator's responsibility. Take application-specific influences into account, such as:

- Dirt blocking the pneumatic connections
- Corrosion (destruction primarily of metals due to chemical and physical processes)
- Material fatigue
- Aging (damage caused to organic materials, e.g. plastics or elastomers, by exposure to light and heat)
- Chemical attack (organic materials, e.g. plastics or elastomer, which swell, leach out or decompose due to exposure to chemicals)

NOTICE

Risk of malfunction due to the use of unauthorized parts.

→ Only use original parts to replace worn parts.

6.2 Function testing

Regularly check the safety function according to the test plan drawn up by the operator.

i Note

Record any positioner faults and e-mail (aftersalesservice@samsongroup.com) them to SAM-SON.

Emergency venting by applying a 0 mA signal to terminals 11/12 (control signal):

- Apply supply air within the permissible range (max. 7 bar) to the positioner which allows the valve to move to the maximum travel.
- 2. Connect an electric input signal ≥3.6 mA to the positioner (terminals 11/12).
- 3. Switch the positioner to automatic mode (if it has not already been done).
- 4. Set the input signal (terminals 11/12) over a local current source or over the control system in such a way that the valve moves to the operating position. Check whether the valve moves to this position.
- Set the electric input signal to 0 mA or disconnect it.
 This must cause the valve to move to its fail-safe position (terminals 11/12).
- 6. Check whether the actuator is fully vented within the demanded time.
- 7. Set the input signal (terminals 11/12) over a local current source or over the control system in such a way that the valve moves to the approx. 50 % of its travel. Check whether the valve moved to this position.
- 8. Set the electric input signal to 0 mA or disconnect it.

 This must cause the valve to move to its fail-safe position (terminals 11/12).
- 9. Check whether the actuator is fully vented within the demanded time.



Connect a pressure gauge to check that the actuator has completely vented.

Proof test

A full stroke test must be performed as the proof test. The following value can be used for Proof Test Coverage to calculate PFD_{ava} :

PTC (Proof Test Coverage) = 92 % for a proof test

7 Maintenance and repair

Only perform the work on the positioner described in EB 8384-0.

NOTICE

Fail-safe action impaired due to incorrect repair.

→ Service and repair work must be performed by trained staff only.

For devices operated in the low demand mode (LDM), a useful lifetime of 11 years (plus 1.5 years storage time) is confirmed by TÜV Rheinland® from the date of manufacture while taking into account the specific conditions of use specified in the Safety Manual and the Mounting and Operating Instructions.

The results of the proof test must be assessed and the maintenance scheduled based on it. In particular, after changes (e.g. signs of ageing in elastomers, changed switching times or leakage etc.), it is essential that the manufacturer performs maintenance or repair work on the device.

MTC (Maintenance Coverage) > 99 %

8 Safety-related data and certificates

The safety-related data are listed in the following certificate.





SIL/PL Capability

www.buv.com ID 0600000000

No.: 968/V 1161.00/20

Product tested

Electro pneumatic positioners

Certificate holder

SAMSON AG Weismüllerstr. 3

60314 Frankfurt / Main

Germany

Type designation

3730-0, 3730-1, 3730-2, 3730-3, 3730-4, 3730-5, 3730-6, TROVIS SAFE 3730-6

3731-3, TROVIS SAFE 3731-3, 3731-5

Codes and standards

IEC 61508 Parts 1-2 and 4-7:2010

Intended application

Safety Function: Safe venting (and safe indication of the end positions)

The positioners are suitable for use in a safety instrumented system up to

SIL 2 (low demand mode).

Under consideration of the minimum required hardware fault tolerance HFT = 1 the positioners may be used in a redundant architecture up to SIL 3 according to IEC 61508 and IEC 61511:2016 + AMD1:2017.

Specific requirements

The instructions of the associated Installation, Operating and Safety

Manual shall be considered.

Summary of test results see back side of this certificate.

Valid until 2025-05-04

and application requires prior

are registers diredemarks.

TUEV and TUV

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The issue of this certificate is based upon an examination, whose results are documented in Report No. 968/V 1161.00/20 dated 2020-05-04.

This certificate is valid only for products which are identical with the product tested.

TÜV Rheinland Industrie Service GmbH Bereich Automation

Köln, 2020-05-04

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Holder: SAMSON AG

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Product tested: Electropneumatic positioners

3730-0, 3730-1, 3730-2, 3730-3, 3730-4, 3730-5,

3730-63, TROVIS SAFE 3730-63

3731-34, TROVIS SAFE 3731-34, 3731-5

Results of Assessment

Hardware Fault Tolerance	HFT	0
Route of Assessment		2 _H / 1 _S
Type of Sub-system		Type A
Mode of Operation		Low Demand Mode

Safe venting via I/p-converter- all above mentioned types with or without

Lambda Dangerous Undetected 1	λ _{DU}	9.58 E-08 / h	96 FIT	
Average Probability of Fallure on Demand 2	PFD _{ave} (T ₁)	4.19 E-	-04	

Safe venting via forced venting (3730-6, TROVIS SAFE 3730-6)

Lambda Dangerous Undetected 1	λου	9.58 E-08 / h	96 FIT
Average Probability of Fallure on Demand ²	PFD _{avg} (T ₁)	4.19 E-	-04

Safe venting solenoid valve (3730-2, 3730-3, 3730-4, 3730-	5, 3730-6, TRO	VIS SAFE 3730-6)	Υ
Lambda Dangerous Undetected 1	λ _{DU}	8.83 E-08 / h	Ja FIT
Average Probability of Fallure on Demand 2	PFD _{avg} (T ₁)	3.87 E	-04

Safe Indication of the end positions (3730-1, 3730-2, 3730-3, 3730-4, 3730-5, 3730-6, TROVIS SAFE 3730-6)

Lambda Dangerous Undetected 1	λ _{DU}	7.43 E-08 / h	74 FIT
Average Probability of Fallure on Demand 2	PFD _{ave} (T ₁)	3.26 E	-04

¹ assumed Diagnostic Coverage DC = 0 %

Origin of values

The stated failure rates are the result of an FMEDA with tailored failure rates for the design and manufacturing

Furthermore the results have been verified by qualification tests and field-feedback data of the last 5 years.

Failure rates include failures that occur at a random point in time and are due to degradation mechanisms such as ageing.

The stated failure rates do not release the end-user from collecting and evaluating application-specific reliability data.

Systematic Capability

The development and manufacturing process and the functional safety management applied by the manufacturer in the relevant lifecycle phases of the product have been audited and assessed as suitable for the manufacturing of products for use in applications with a maximum Safety Integrity Level of 3 (SC 3).

Periodic Tests and Maintenance

The given values require periodic tests and maintenance as described in the Safety Manual.

The operator is responsible for the consideration of specific external conditions (e.g. ensuring of required quality of media, max. temperature, time of impact), and adequate test cycles.

TÜV Rheinland Industrie Service GmbH, Am Grauen Stein, 51105 Köln / Germany

² assumed Proof Test Interval T₁ = 1 year

³ The types 3730-6 and TROVIS SAFE 3730-6 optionally have switch-off thresholds of < 3.8 mA or < 4.4 mA

The types 3731-3 and TROVIS SAFE 3731-3 optionally have switch-off thresholds of < 3.8 mA</p>

